

Status Report on Development of Random Polishing Process

Christina Dunn and John Kelchner

Zeeko Technologies, LLC 3495 Kent Avenue, Suite K-100 West Lafayette, IN 47906 Tel: 765-775-1010





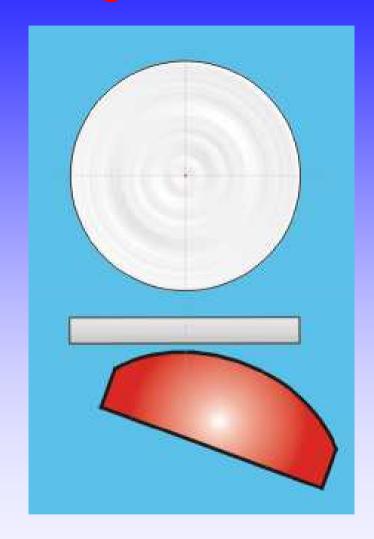
Outline

- Brief overview of the Zeeko process and the random tool path
- Possible applications of the random tool path
- Polishing experiments with the random tool path
- Future work



Basis of the Zeeko Polishing Process

- Spherical "bonnet" creates a localized area of material removal of variable size ("influence function")
- Spot size is controlled independently by varying:
 - The axial position of the tool WRT the part, and therefore the degree to which the membrane is compressed against the part
 - The internal pressure of the working fluid within the tool is controlled separately





Tooling

The spherical bonnet tooling:

- is covered with standard polishing pads (e.g. polyurethane)
- is pressed into the surface of the workpiece by displacement ∆z, creating a contact spot of known diameter
- is worked with standard polishing consumables (e.g. cerium oxide)
- delivers volumetric removal rates up to a few cubic millimeters per minute

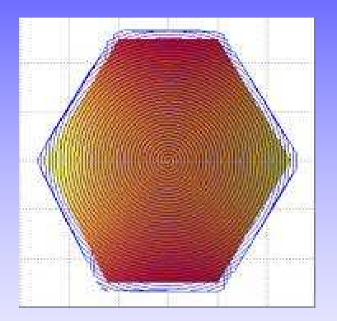


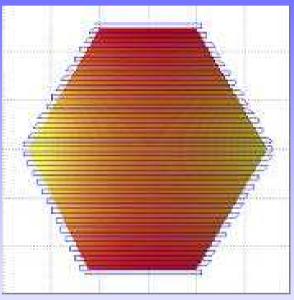
Zeeko Polishing Modes

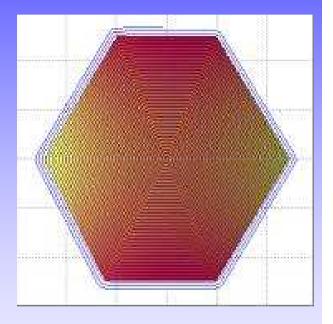
- Pre-polishing uniform removal across surface with constant feed rate
- Corrective Polishing the tool's dwell time is varied to provide a prescriptive polish
- "Grolishing" a diamond pad is used to severely abrade the surface as a polishing process. This replaces the usual pads and polishing slurries.



Tool paths



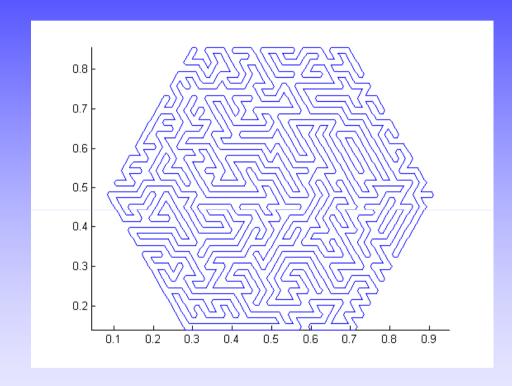






The unicursal random tool path

- Never crosses itself
- Completely new pattern with each iteration
- Can be used with any continuous surface
- This tool path is compatible with Zeeko's Precessions software for corrective polishing





A comparison between raster and random tool paths

- Two 20-mm diameter spots were polished on a pitch-polished flat part
- The pattern spacing on both paths was 0.35 mm.
- All other parameters were equal.

Feed rate: 100 mm/min

H-axis speed: 300 rpm

Precess angle: 15°

10 mm spot

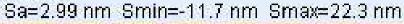
80 mm bonnet

Z-offset: 0.16 mm

Polishing time: 30 min



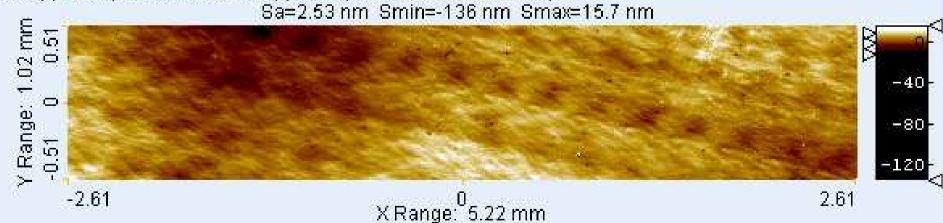






Random polished region

C:\Copy of MapvueAE\DataC:\Copy of MapvueAE\Data\TEMP.map

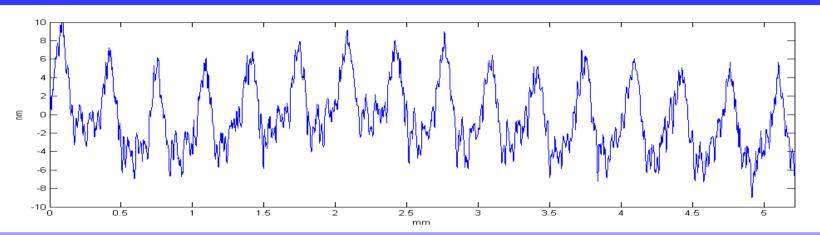


June 17, 2009

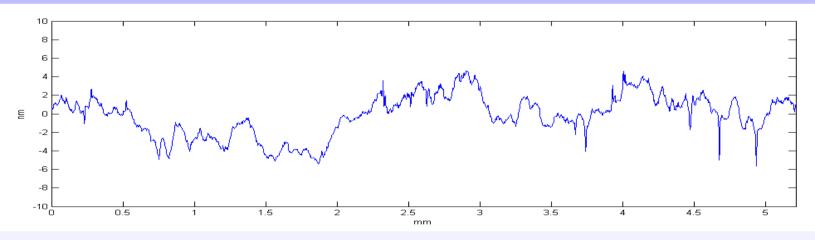
Mirror Technology Days



Raster polished region profile



Random polished region profile



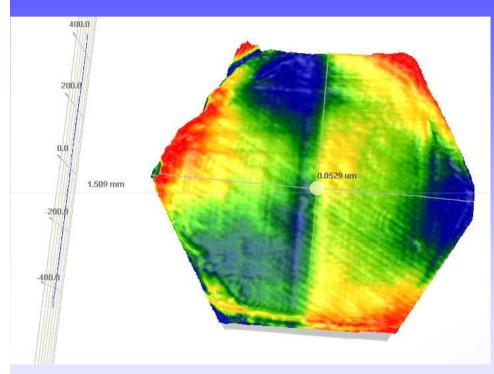


Possible Applications of the Random Tool Path

- Pre-polishing: remove a uniform-depth layer of material across the entire surface to correct sub-surface damage
 - High removal rates desirable
- Surface clean-up: remove a uniform-depth layer of material to clean up surface after corrective polishing
- Corrective polishing



Fabrication of Large Telescope Mirror Segments



Result from Guoyu Yu, OpTIC Technium

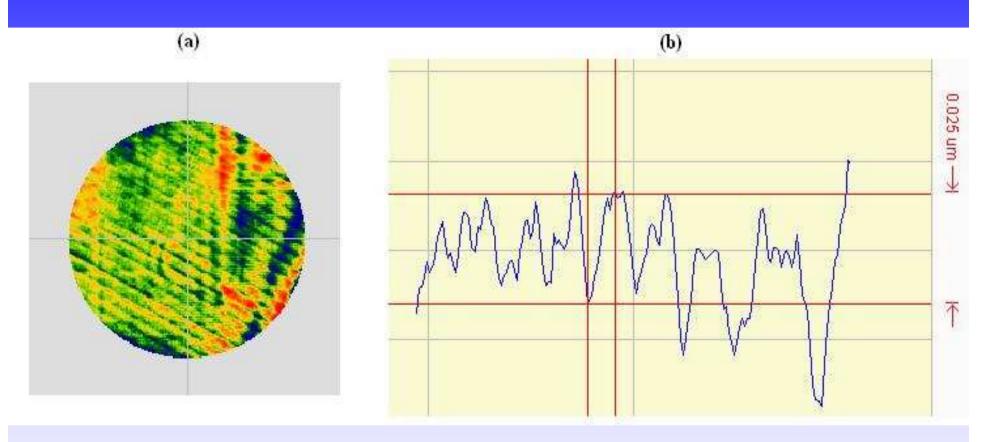
- Removing subsurface damage on such a large part requires a high removal rate
- Grolishing removes material efficiently, but leaves a strong signature.

June 17, 2009

Mirror Technology Days



Raster marks left by grolishing process



Result from Guoyu Yu, OpTIC Technium



Uniform Removal with the Random Tool Path

- Polished a 60-mm diameter circle on 80mm diameter plano part
- 24 minute polishing program
- H-axis speed: 200 rpm
- Feed rate: 750 mm/min
- Four precess positions (angled at 15°)



Ra: 99.65 nm

Rq: 118.93 nm Rz: 540.98 nm

Rt: 553.62 nm

Set-up Parameters:

Size: 736 X 480

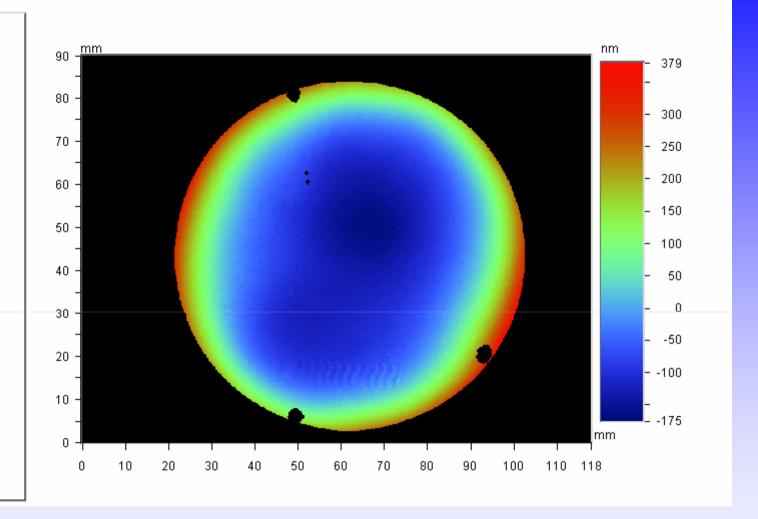
Sampling: 160.54 um

Processed Options:

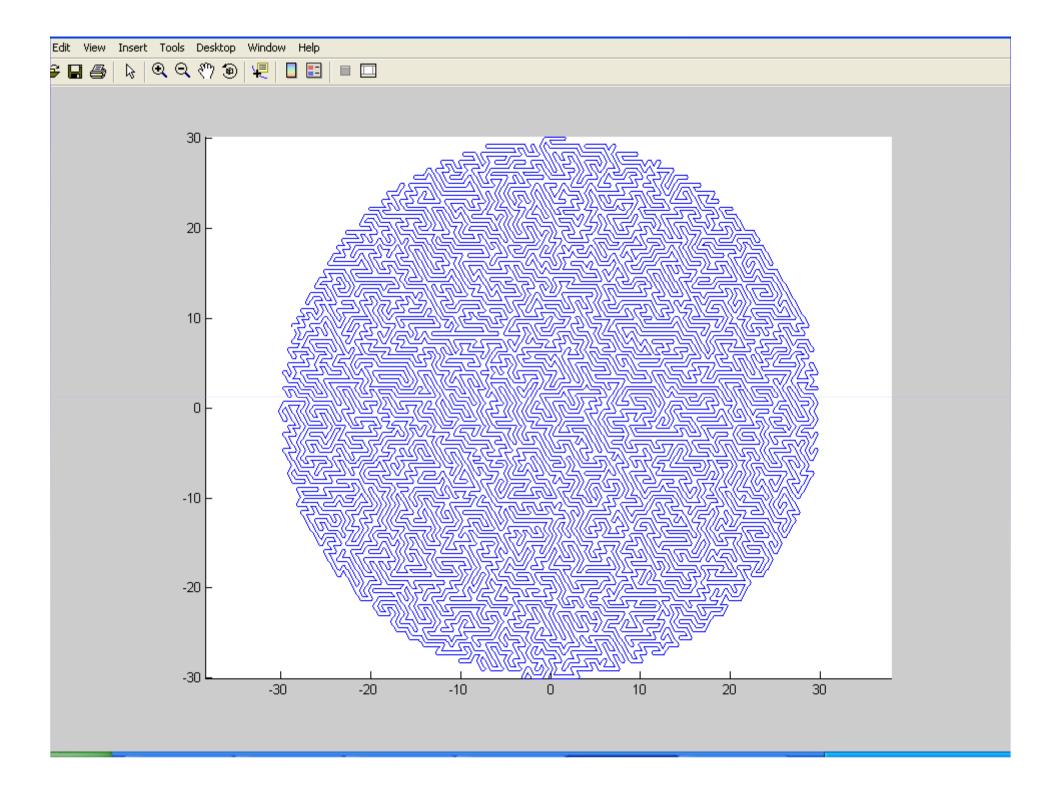
Terms Removed:

Tilt

Filtering:







Ra: 415.81 nm

Rq: 441.29 nm

Rz: 1.29 um

Rt: 1.30 um

Set-up Parameters:

Size: 736 X 480

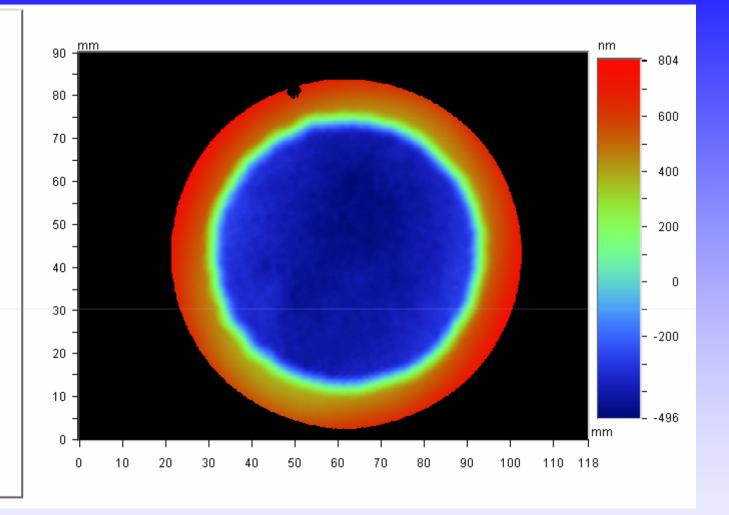
Sampling: 160.71 um

Processed Options:

Terms Removed:

Tilt

Filtering:





Ra: 318.52 nm

Rq: 332.92 nm

Rz: 804.54 nm

Rt: 814.19 nm

Set-up Parameters:

Size: 736 X 480

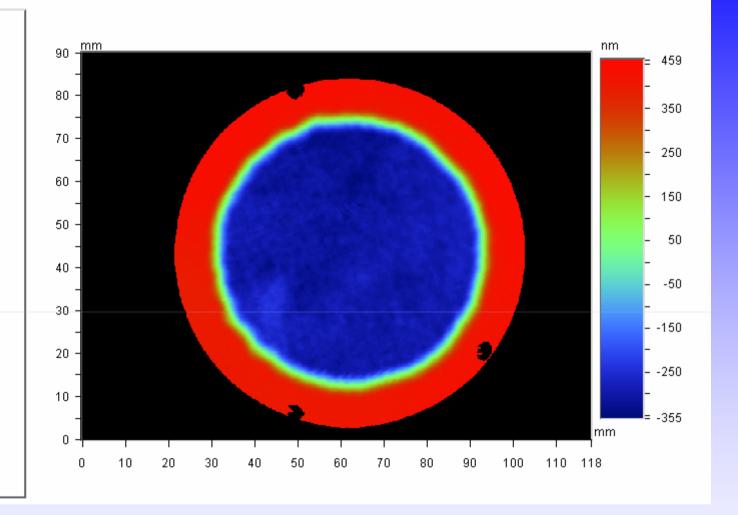
Sampling: 160.71 um

Processed Options:

Terms Removed:

Tilt

Filtering:





Ra: 11.56 nm

Rq: 14.94 nm

Rz: 102.68 nm

Rt: 118.34 nm

Set-up Parameters:

Size: 736 X 480

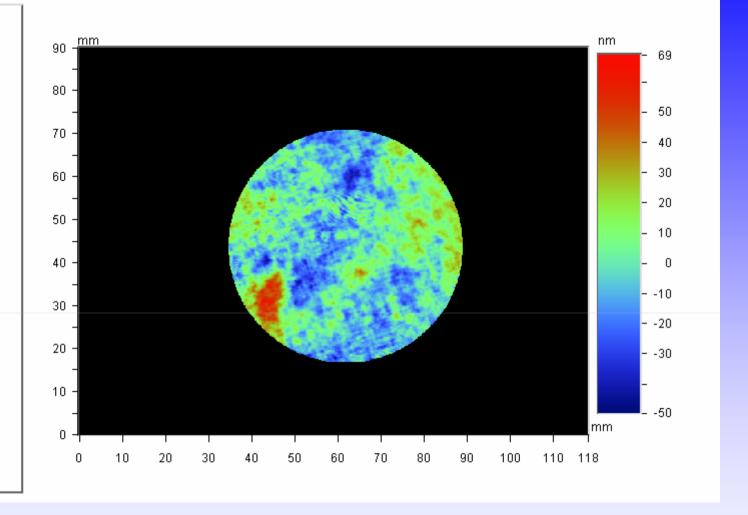
Sampling: 160.71 um

Processed Options:

Terms Removed:

Tilt

Filtering:

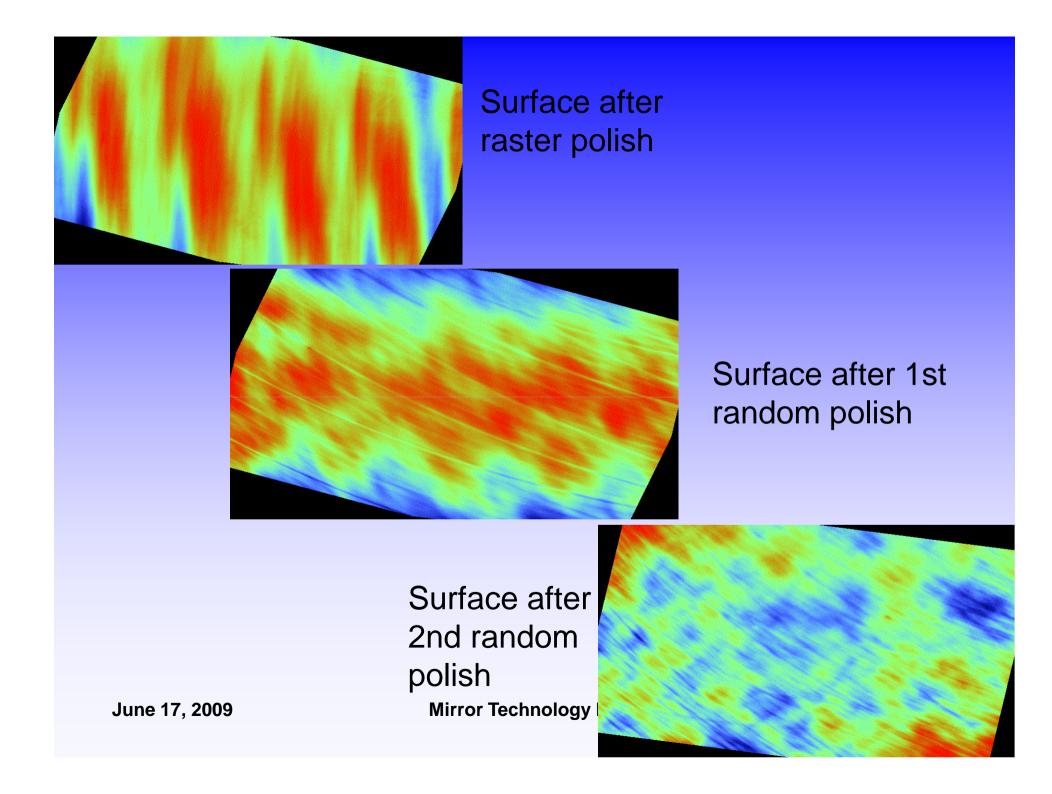




Clean up experiment with random tool path

- Glass flat was polished with a raster path to produce a surface with a periodic mid-spatial frequency feature.
- This region was then re-polished twice using random tool paths, resulting in an improvement in surface texture.





Surface texture statistics

	Ra (nm)	Rq (nm)	Rt (nm)
Rastered surface	8.10	10.29	114.47
After 1st random polish	6.55	7.85	43.37
After 2nd random polish	3.95	5.24	35.21



Uniform removal

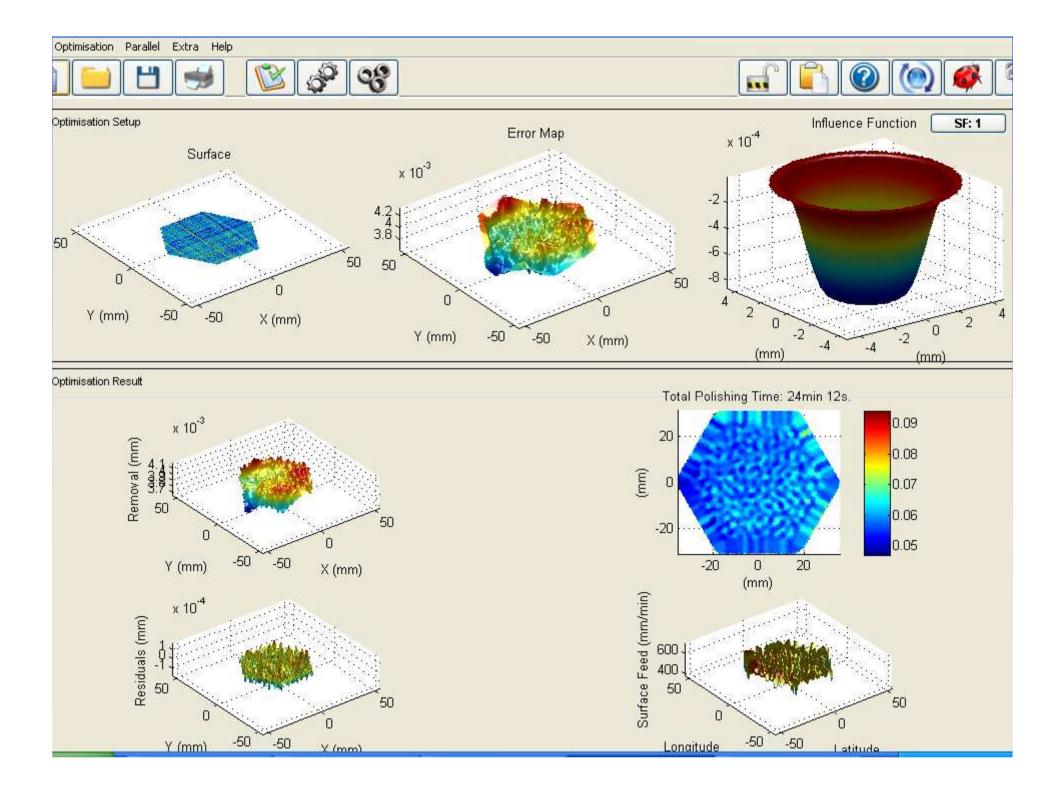
- For pre-polishing, we need a higher removal rate
 - Experiments are planned to find parameters that maximize the removal rate
- For a clean up step, we need a better finish
 - Experiments are planned to repeat this same procedure with a pitch tool



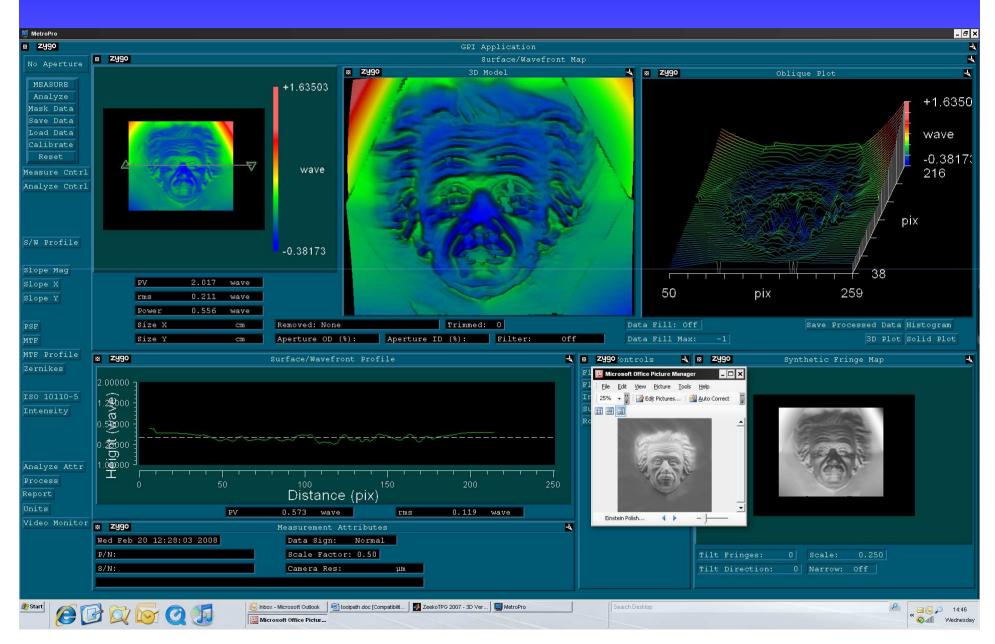
Correcting with the Random Tool Path

- Successful correction of surfaces with the random tool path depends on the ability to deliver the correct dwell times at the correct locations.
- Zeeko's Precessions software is capable of optimizing dwell time maps to produce very complex corrections.





Zeeko Freeform



Ra: 275.14 nm

Rq: 317.78 nm

Rz: 1.17 um

Rt: 1.18 um

Set-up Parameters:

Size: 736 X 480

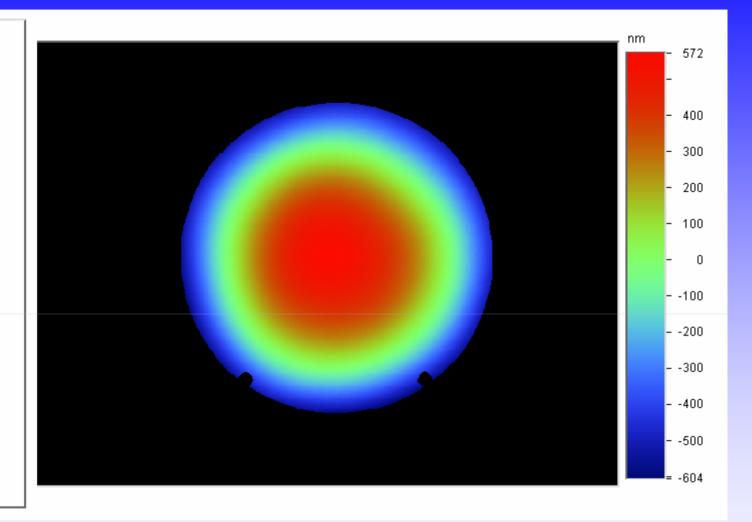
Sampling: 0.00 mm

Processed Options:

Terms Removed:

Tilt

Filtering:





Ra: 73.15 nm Rq: 88.73 nm Rz: 510.98 nm Rt: 579.64 nm

Set-up Parameters:

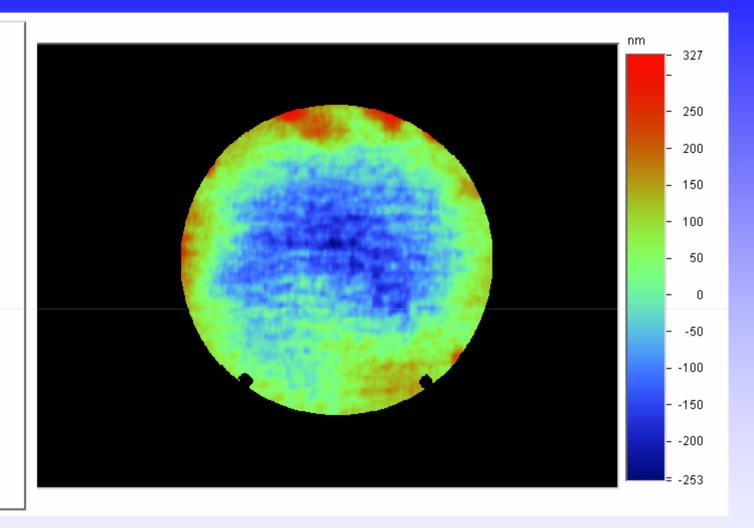
Size: 736 X 480 Sampling: 0.00 mm

Processed Options:

Terms Removed:

Tilt

Filtering:





Ra: 29.92 nm Rq: 40.62 nm Rz: 367.56 nm Rt: 429.68 nm

Set-up Parameters:

Size: 736 X 480

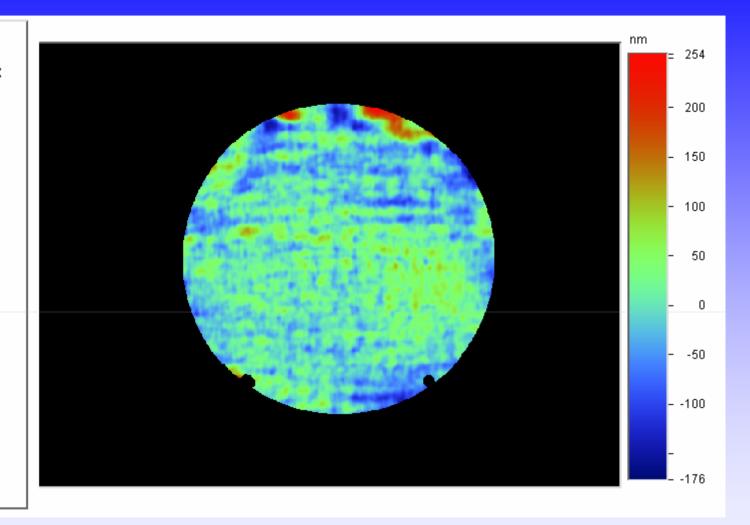
Sampling: 0.00 mm

Processed Options:

Terms Removed:

Tilt

Filtering:





Correcting with Random Tool Path

- At the moment, the application of the dwell time map using the random tool path is not accurate enough to produce results which rival the Zeeko process with a raster tool path.
- Both the accuracy of position and velocity tool must be improved during the random polish.



Conclusions and Future Work

- The most viable use of the random tool path is the clean-up step, requiring testing with a pitch tool and better slurry delivery.
- The next application to develop is prepolishing, requiring increasing the removal rate.
- The processes could be used in concert with the standard tool paths, using these tool paths for correction and random for pre- and post-processing.



Acknowledgements

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